

Education


- 2022–present **Ph.D. in Computer Science**, *Brown University*, USA, CGPA - 4.0 / 4.0
- 2017–2022 **Bachelor of Technology and Master of Science by Research in Electronics and Communication**, *International Institute of Information Technology*, Hyderabad, India, CGPA - 9.1/10, **(Gold Medal)**
- 2015–2017 **Senior Secondary School**, *Delhi Private School*, Sharjah, United Arab Emirates, Grade - 96/100

Research Experience





- 2023–2024 **Applied Scientist (Part-Time)** Amazon Robotics, North Reading, Massachusetts, USA
Advisors: [Jeoren Vanbaar](#), [Kapil Katyal](#), [Srinath Sridhar](#)
- Baked 3D geometry in text-to-image diffusion models using [GeoDiffuser](#) for geometry editing without any fine-tuning. | PyTorch, PyTorch3D
 - Improved item identification of occluded items by 4% for targeted robot picking using diffusion inpainting. Trained diffusion model to generate real-world tote images from layouts and text prompts.
 - Experimented with abstract textual-inversion tokens for novel view synthesis and re-posing of objects.
- 2021–2022 **Research Intern (Remote)** *Brown Visual Computing*, *Brown University*, USA
Advisor: [Srinath Sridhar](#) and [Leonidas J. Guibas](#)
- Worked on pose-equivariant architectures for unsupervised canonicalization of full and partial 3D point clouds. See [ConDor!](#) | PyTorch, Tensorflow
- 2019–2022 **Research Assistant**, *Robotics Research Center (RRC)*, *IIT*, Hyderabad, India
Advisor: [K. Madhava Krishna](#)
- Designed, implemented, and brainstormed on weakly-supervised dense canonicalization technique [DRACO](#) to eradicate the need for ground-truth canonical maps to reduce the sim2real gap. | PyTorch, Open3D
 - Proposed and implemented trajectory scaling method to scale the ego-trajectory to the absolute trajectory for monocular SLAM pipeline by leveraging features on the ground. | OpenCV
 - Designing and building the perception for the Autonomous Driving Car. | Raspberry Pi, ROS

Publications




2024

- [P.9] **Rahul Sajnani**, Jeroen Vanbaar, Jie Min, Kapil Katyal, Srinath Sridhar. *GeoDiffuser: Geometry-Based Image Editing with Diffusion Models*. IEEE Winter Conference on Applications of Computer Vision (**IEEE WACV 2025**). 

2023




- [P.8] Rohith Agaram, Shaurya Dewan, **Rahul Sajnani**, Adrien Poulernard, Madhava Krishna, Srinath Sridhar. *Canonical Fields: Self-Supervised Learning of Pose-Canonicalized Neural Fields*. IEEE Conference on Computer Vision and Pattern Recognition (**IEEE CVPR 2023 (Highlight)**).  
- [P.7] Qihong Anna Wei, Sijie Ding, Jeong Joon Park, **Rahul Sajnani**, Adrien Poulernard, Srinath Sridhar, Leonidas Guibas. IEEE Conference on Computer Vision and Pattern Recognition (**IEEE CVPR 2023**).  

2022

- [P.6] **Rahul Sajnani**, Adrien Poulernard, Jivitesh Jain, Radhika Dua, Leonidas J. Guibas, Srinath Sridhar. IEEE Conference on Computer Vision and Pattern Recognition (**IEEE CVPR 2022**).  
- [P.5] Aadil Mehdi J Sanchawala*, Adhithya Arun*, **Rahul Sajnani***, Rohan Chacko*, Kavita Vemuri. *Exploring Empathy and a Range of Emotions Towards Protest Photographs*. Proceedings of Cognitive Science Society 

¹Icons & underlined text are clickable links.





2021

- [P.4] **Rahul Sajnani***, Aadil Mehdi Sanchawala*, Krishna Murthy Jatavallabhula, Srinath Sridhar, K. Madhava Krishna. *DRACO: Weakly Supervised Dense Reconstruction And Canonicalization of Objects*. IEEE International Conference on Robotics and Automation (**IEEE ICRA 2021**)  
- [P.3] Swapnil Daga, Gokul B. Nair, Anirudha Ramesh, **Rahul Sajnani**, Junaid Ahmed Ansari, K. Madhava Krishna. *BirdSLAM: Monocular Multibody SLAM in Bird's-Eye View*. International Conference on Computer Vision Theory and Applications (**VISAPP 2021**) 

2020

- [P.2] Aadil Mehdi J Sanchawala*, Adhithya Arun*, **Rahul Sajnani***, Kavita Vemuri. *Unlocked: A Game On Human Trafficking*. IEEE Conference on Games (**IEEE CoG 2020**) [**nominated for best paper, featured in IIIT blog and Times of India**]   
- [P.1] Gokul B. Nair, Swapnil Daga, **Rahul Sajnani**, Anirudha Ramesh, Junaid Ahmed Ansari, Krishna Murthy Jatavallabhula, K. Madhava Krishna. *Multi-object Monocular SLAM for Dynamic Environments*. IEEE Intelligent Vehicles Symposium (**IEEE IV 2020**)  

Leadership

- 2021–2022 **Founder and Coordinator**, *The Skateboard Club, IIIT*, Hyderabad, India
- Founded the skateboarding club and held skateboarding events catering to over 80-100 enthusiasts.
 - Obtained funds for the club and taught students how to skateboard.
- 2021–2022 **Head System Administrator**, *Robotics Research Center (RRC), IIIT*, Hyderabad, India
- Implemented incremental cloud & local backup. | Rsnapshot, Restic
 - Server monitoring and management. | Grafana, Prometheus, Atop
 - Customized servers to achieve zero downtime.
 - Rapidly transferred users to different computing clusters after server fire without losing data.
 - Maintaining lab [website](#). | Jekyll
- 2019–2021 **Advisor and Team Lead**, *The Dance Crew, IIIT*, Hyderabad, India    
- Expanded the crew from 5 coordinators to over 30 members and bifurcated them into multiple roles for better organization.
 - Planned and held workshops and events.
 - Interviewed new candidates to carry the crew's legacy forward and make them self-sufficient.
- 2019–2020 **House Captain**, *Aakash House, IIIT*, Hyderabad, India
- Assisted students in house activities and led the band, dance, and skit practice sessions.
- 2016–2017 **Vice President Cultural (Arts)**, *DPS Sharjah, UAE*
- Organized annual and quarterly cultural events that included art, dance, and music.




Service

Reviewer CVPR, ICCV, ECCV, T-PAMI, ICLR, ACCV, TVCG.






Awards

- 2022 Gold Medal (IIIT-H): Highest CGPA in ECD Stream.
- 2020–2021 Research Award (IIIT-H): Awarded to top 20 research students in the institute.
- 2019–2021 Dean's list and Merit list Award (IIIT-H): Awarded to top 5% of students in the institute with good academic standing.
- 2018 Selected for BountyCon organized by Facebook and Google held in Singapore. BountyCon is an invitation-only security conference wherein you hack Facebook and Google for bounty.
- 2017 Academic Trophy (DPS Sharjah): Awarded to top 15 students in the school.

Teaching Experience

- 2019–2021 **Teaching Assistant**, *IIIT*, Hyderabad, India
- TA for Mobile Robotics, Digital Systems and Micro-controllers, and Electronics Workshop-2
 - Conducted tutorial sessions, graded assignments, and exam papers.
- Summer 2021 **Head Organizer of Robotics Summer School**, *Robotics Research Center (RRC)*, *IIIT*, Hyderabad, India
- Planned and scheduled the Robotics Research Center Summer School for teaching lab entrants about Robotics and Computer Vision. 
 - Taught concepts such as Multi-View Geometry, Transformations, Camera Modeling, Optimization, and Remote Server Usage basics.  

Selected Projects

- August 2021 **Robotics Planning and Navigation** 
- Implemented planning and navigation algorithms such as Rapidly Exploring Random Trees, dynamic collision avoidance using Collision Cones formulation, and Model Predictive Control.
- April 2021 **Reinforcement Learning for Source Seeking** 
- Implemented and simulated an autonomous drone in AirSim to find and reach the source of the heat signature. Implemented Q learning, DQN, and DDPG. | AirSim, PyTorch-Lightning, and PyTorch
- November 2020 **Cross-Lingual Reverse Dictionary Mapping** 
- Implemented dictionary mapping by fine-tuning IndicBert to map phrases given in 6 native Indian languages to the closest word embedding in the target language. | PyTorch-Lightning, PyTorch, and Faiss
- September 2020 **Wikipedia Search Engine** 
- Created a reverse index to search 45 GB of wiki data within a few seconds.
- April 2020 **3D Reconstruction from Accidental Motion** 
- Reconstructed the scene from accidental motion, which involves performing bundle adjustment followed by conditional random field optimization to obtain dense scene depth. | OpenCV, Ceres Solver

Skills

- Languages Python, MATLAB, C/C++, \LaTeX
- Libraries PyTorch, Tensorflow, OpenCV, Ceres Solver, Open3D, PyTorch-Lightning, Hydra, Faiss, TorchText
- Software ROS, Git, Bash, Blender, Adobe Premiere Pro, Adobe illustrator, Audacity
- Hobbies Dancing, Playing Keyboard, Skateboarding *Rare*: Ethical Hacking